

CLAIMS

What is claimed is:

5 1. A robotic domain reflectometry test system comprising:
domain reflectometry instrumentation;
a robotic arm; and
a passive, high frequency probe assembly comprising a signal probe and a
ground probe having a fixed, non-adjustable pitch, said probe assembly being electrically connected to
said domain reflectometry instrumentation, and being moved, electrically connected to, and retracted
from test points on an electrical component to be tested by said robotic arm.

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15 2. The system of claim 1 additionally comprising a second robotic arm and a second
passive, high frequency probe assembly having a fixed, non-adjustable pitch and being electrically
connected to said domain reflectometry instrumentation, and being moved, electrically connected to, and
retracted from test points on the electrical component to be tested by said second robotic arm, whereby
differential domain reflectometry tests may be performed on the electrical component.

20 3. The system of claim 1 wherein said probe assembly comprises a second signal probe
and a second ground probe having a fixed, non-adjustable pitch, whereby differential domain
reflectometry tests may be performed on the electrical component.

25 4. The system of claim 1 additionally comprising a probe assembly changing station
accessible by said robotic arm, said probe assembly changing station comprising holders for a plurality
of probe assemblies.

Not shown

no

*involving
use of two
separate probe assemblies*

5. The system of claim 4 additionally comprising a robotic control system comprising means for directing said robotic arm to acquire from said probe assembly changing station a probe assembly having a correct pitch for testing of test points of the electrical component having a same pitch.

5 6. The system of claim 1 additionally comprising a calibration/verification station accessible by said robotic arm and comprising a calibrated airline.

7. The system of claim 1 wherein said system can test traces having a length of between approximately 0.5 inches and 150 feet such that a standard deviation of domain reflectometry test result impedances is 0.03 ohms or less.

8. The system of claim 1 wherein said probe assembly mimics electrical characteristics of a coaxial structure.

9. The system of claim 1 wherein said system can test components comprising dimensions of between approximately 5.25 inches x 0.5 inches and 36 inches x 28.5 inches.

10. The system of claim 1 additionally comprising a robotic control system comprising means for automatically planning testing of the electrical component by importation of computer aided design data for the electrical component.

CAD

11. The system of claim 1 wherein said system records impedance and propagation delay and calculates a dielectric constant for each test point of the electrical component.

12. A probe assembly changing station for a robotic domain reflectometry test system, said station being accessible by a robotic arm of said system, and said station comprising holders for a plurality of passive, high frequency probe assemblies affixable to an end of the robotic arm and from which the robotic arm can without human intervention affix any of the plurality of probe assemblies.

13. The probe assembly changing station of claim 12 wherein each of said probe assemblies comprises a passive, high frequency probe assembly comprising a signal probe and a ground probe having a fixed, non-adjustable pitch.

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14. A robotic domain reflectometry test system comprising:
differential domain reflectometry instrumentation;
at least one robotic arm; and
two passive, high frequency probe assemblies each comprising a signal probe,
each said probe assembly being electrically connected to said differential domain reflectometry instrumentation, and being moved, electrically connected to, and retracted from test points on an electrical component to be tested by said at least one robotic arm.

no
gm.
note

15. The system of claim 14 wherein said at least one robotic arm comprises a single robotic arm holding both said probe assemblies.

16. The system of claim 14 wherein said at least one robotic arm comprises two robotic arms each holding one of said probe assemblies.

17. The system of claim 14 wherein at least one of said probe assemblies additionally comprises a ground probe having a fixed, non-adjustable pitch with respect to said signal probe on said at least one of said probe assemblies.

18. The system of claim 17 wherein both of said probe assemblies additionally comprise a ground probe having a fixed, non-adjustable pitch.

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Fig. 12
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points and means for calculating and recording a dielectric constant for each test of the test points.

0.03 ohms or less.

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12-12-87
1-1-88

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21. A robotic domain reflectometry test system comprising:

domain reflectometry instrumentation;

a robotic arm;

a passive, high frequency probe assembly comprising a signal probe and a

5 ground probe, said probe assembly being electrically connected to said domain reflectometry instrumentation, and being moved, electrically connected to, and retracted from test points on an electrical component to be tested by said robotic arm; and

a calibration/verification station accessible by said robotic arm and comprising a calibrated airline.

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22. The system of claim 20 wherein said calibrated airline is selected from the group consisting of 28 ohm and 50 ohm NIST calibrated airlines.

23. *Method of 1*
A robotic domain reflectometry test method comprising the steps of:
providing to a robotic arm a passive, high frequency probe assembly comprising
15 a signal probe and a ground probe having a fixed, non-adjustable pitch, the probe assembly being electrically connected to domain reflectometry instrumentation; and
with the robotic arm moving the probe assembly proximate to, electrically
connecting the probe assembly to, and retracting the probe assembly from test points on an electrical
20 component to be tested.

24. *Method of 2*
A robotic domain reflectometry test method comprising the steps of:
providing within reach of a robotic arm a probe assembly changing station
comprising holders for a plurality of passive, high frequency probe assemblies;
25 without human intervention affixing to an end of the robotic arm any one of the plurality of probe assemblies.

A robotic domain reflectometry test method comprising the steps of:

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probe

5 instrumentation; and

26. A robot

A robotic domain reflectometry test method comprising the steps of:

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recording impedance and propagation delay for each test of the test points and calculating and recording a dielectric constant for each test of the test points.

Method
of 20

27. A robotic domain reflectometry test method comprising the steps of:

providing to a robotic arm a passive, high frequency probe assembly comprising a signal probe and a ground probe, the probe assembly being electrically connected to domain reflectometry instrumentation;

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with the robotic arm moving the probe assembly proximate to, electrically connecting the probe assembly to, and retracting the probe assembly from test points on an electrical component to be tested; and

testing traces of the electrical component having a length of between approximately 0.5 inches and 150 feet such that a standard deviation of domain reflectometry test result impedances is 0.03 ohms or less.

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Method
of 21

28. A robotic domain reflectometry test system comprising the steps of:

providing to a robotic arm a passive, high frequency probe assembly comprising a signal probe and a ground probe, said probe assembly being electrically connected to domain reflectometry instrumentation;

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with the robotic arm moving the probe assembly proximate to, electrically connecting the probe assembly to, and retracting the probe assembly from test points on an electrical component to be tested; and

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employing a calibration/verification station accessible by the robotic arm and comprising a calibrated airline.